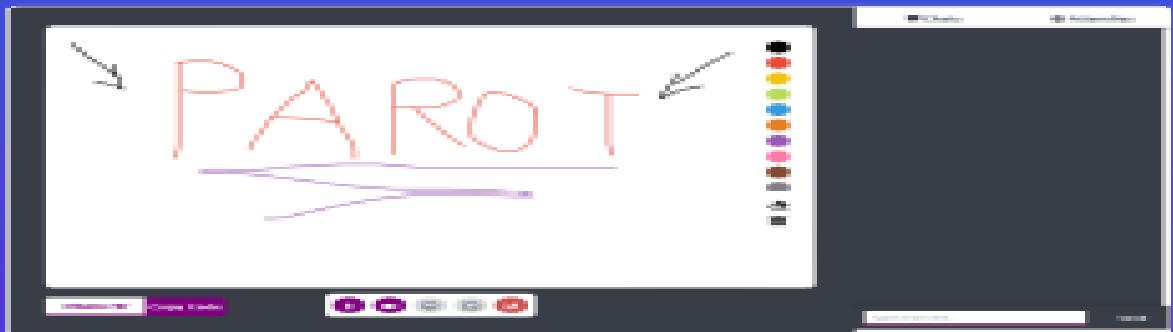




PAROT System

Its purpose is to facilitate the sharing and retrieval of educational resources in PDF format and to improve educational interactions between teachers and students. A user-friendly web-based platform for enhanced student-teacher connectivity is one of the main goals, offering tutorial videos to new users, and putting in place an attendance tracking system for student safety. A user-friendly dashboard, messaging tools for direct communication, scheduling, secure login and authentication, user registration and profile management, PDF file upload with efficient organization and strong data security and privacy measures are some of the system's key features.

Our graduation project utilized HTML, CSS, Tailwind, NodeJS, and MongoDB. HTML and CSS provided the structural and stylistic foundation, with Tailwind CSS enabling rapid and responsive design through its utility-first approach. NodeJS facilitated a high-performance, scalable backend, while MongoDB offered flexible, schema-less data storage. This tech stack ensured efficient development and robust application performance. Tailwind CSS accelerated design, NodeJS and MongoDB provided scalability and flexibility, and HTML/CSS contributed to a polished user interface, resulting in a user-friendly, high-performing web application.



This Integrated School Management System holds promise in transforming traditional educational environments by fostering stronger connections between students and teachers and optimizing the distribution and retrieval of educational resources. Its potential to revolutionize educational workflows underscores its importance as a valuable tool in modernizing and improving educational practices.



QR Code for student



Online session



Study With AI



Pomodoro



Payment System

Supervisors :

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A VIRTUAL PET FOR CHILDREN WITH AUTISM SPECTRUM DISORDERS (ASD)

ABSTRACT

In Egypt, about 23.6% of children with developmental disabilities have Autism Spectrum Disorder (ASD), social challenges are particularly acute for those with Asperger syndrome, often leading to marginalization and limited opportunities. This project proposes an innovative solution: an Android application featuring an interactive virtual pet companion powered by augmented reality (AR). Developed with the Unity game engine and MediaPipe for pose estimation, the app aims to provide a safe and engaging platform for children with Asperger syndrome to practice social interaction, develop emotional learning skills, and combat social isolation. This project targets children aged 5-12, seeking to improve their social skills, emotional regulation, and engagement with their surroundings through playful interaction with the virtual pet. By addressing the unique needs of children with Asperger syndrome in the Egyptian context, this project has the potential to foster their social integration and well-being, paving the way for a more inclusive future.

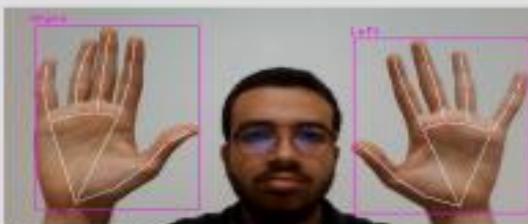
METHODOLOGY

Augmented Reality (AR) technology involves the integration of virtual objects and other digital content with physical or real-world content. This enhances the realism and interactivity of the AR experience significantly. The project utilizes a combination of technologies to create an interactive and immersive AR experience:

- Unity Game Engine: The project is built using Unity, a powerful game engine that enables the creation of 2D AR environments and integrates ARCore for Android Applications.
- ARCore and MediaPipe Pose Estimation: ARCore allows for the projection of virtual objects onto the real world based on real-time body pose estimation, captured using MediaPipe. This ensures natural and intuitive interaction between the user and the virtual objects.
- Firebase: Firebase provides a suite of tools and services for the development and management of mobile applications. In this project, Firebase is used for data synchronization and user management.
- Programming Languages: C# Script is used to interact with Unity within the Visual Studio Code IDE, while Python 3.11.4 implements and controls MediaPipe pose estimation, transmitting data points back to Unity.



The image showcases an XR environment simulator, a sophisticated technology that demonstrates the capability of simulating virtual environments within the Unity game engine. As evident, this component simulates the search for a pivot point to ground the AR character.



The image demonstrates MediaPipe's remarkable ability to capture hand movements and identify landmarks (similar to a skeletal structure).



The image showcases how our code smoothly transfers landmark coordinates to Unity Game Engine in real-time using the UDP protocol. UDP is a user-friendly protocol known for its real-time accuracy. Upon receiving the coordinates, Unity Game Engine actively monitors them and detects collisions between the user's hand and virtual objects (such as candy). These collisions trigger specific actions based on the nature of each object.



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This image showcases parts of the UI design for the app. It is noteworthy that a unique UX/UI design was developed based on medical research on how children with autism interact with applications. Several studies have shown that children with autism tend to engage with happy colors like blue, for instance. Moreover, the design ensures that the child cannot use the app and play with their virtual pet except under parental supervision. The app does not serve as a replacement for traditional therapy but rather as an easy-to-use and engaging mobile assistant.



The above set of images showcases real-life screenshots from the application, where a white cat named Salser seamlessly interacts with a child. The cat moves gently around, explores the child's surroundings, and is brought to life using exceptional AR Core technologies that integrate virtual objects into the real world. Users begin their journey by creating an account and logging in. They can then proceed to the game mode, where they can interact with the cat. If a piece appears, simply extend your hand to grab it and engage with it. The app currently features two games: Candy Collection and Arabic Words Collection.



Under the ISO 9241-210:2018 standard, here we explore usability metrics aligned with the core principles of effectiveness, efficiency, and satisfaction. The initial usability evaluation of the integration yielded promising results.

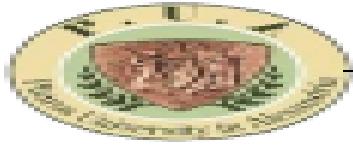
	Result	Indicating
Effectiveness	+	+
Efficiency	+	+
CPU usage	+	+
Memory usage	+	+

CONCLUSION

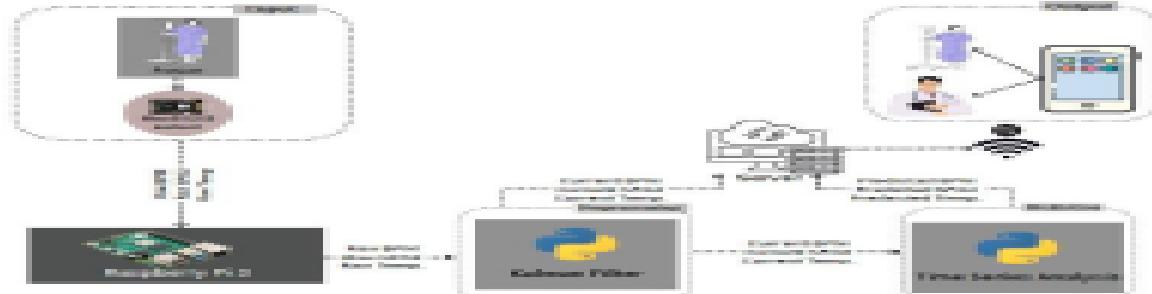
This project presents a novel virtual pet application built with augmented reality and MediaPipe for body detection, aimed at engaging children with ASD and potentially improving their emotional and behavioral development. The prototype successfully captured children's attention and achieved an impressive 92% efficiency and 92% accuracy in its initial model. While these results are promising, further refinement is needed. Future iterations should prioritize enhancing the accuracy of individual virtual pet interactions, particularly in body and behavior detection. Additionally, conducting long-term studies will be crucial in evaluating the sustained effectiveness of such applications on children with ASD.

UNDER SUPERVISION OF:

Dr. Abdelfatah Refat Elshenaway



Smart Heart Rate Tracking Based on Kalman Filter And Time Series Analysis



Abstract

With the rise of heart-related issues such as heart failure, Bradycardia, and Supraventricular Tachycardia, continuous heart rate monitoring is essential. This project creates a real-time heart rate monitoring system using a MAX30200 sensor and a Raspberry Pi. It uses a Kalman filter to enhance data accuracy and time-series analysis to predict future heart rates, providing reliable proactive heart health monitoring without the need for frequent doctor visits.

This methodology monitor continuous heart rate monitoring with the MAX30200 sensor using the Raspberry Pi. The sensor sends data through the WiFi module to measure oxygenated and deoxygenated haemoglobin, creating a real-time heart rate monitoring system. Rapidly, our methodology can predict future heart rates using time-series analysis and Kalman filters. This module makes sure everyone's heart rate is normal. Using this approach, it can measure concentration to detect diseases. An Accelerometer (Gyro) module also sends heart rate data from the Raspberry Pi to predict future values, generating accurate predictions by checking for abnormalities and requesting medical assistance. Our predicted values are communicated to a mobile app via Bluetooth, providing users with reliable insights and notifications, which can help them avoid sudden, unpredictable health issues through early medical intervention.



Methodology

Results



Our application shows the filtered heart rate, unfiltered heart rate and heart rate recorded from three different sensors. The heart rate displayed after filtered heart rate recording is more accurate than the raw heart rate recorded from the three sensors. The recorded heart rate is updated continuously so the latest heart rate is displayed on the screen. The recorded heart rate is stored in the database and the recorded heart rate reading are stored in the database for analysis.

This project presents a heart rate and oxygen saturation monitoring system using Raspberry Pi, MAX30200 sensor, Kalman filter, and time series analysis, providing an effective solution for real-time health tracking and heart rate prediction. The Raspberry Pi processes data, the Kalman filter enhances accuracy, and time series analysis predicts future heart rates. Raspberry enables remote monitoring and communication between devices. This system simplifies primary health checkups for individuals without visiting hospitals regularly, stores medical history for follow-ups, and leverages technology to eliminate human errors, leading to improved performances.

Conclusion



Abstract

Agibot stands at the forefront of agricultural innovation, poised to redefine farming practices burdened by the detrimental effects of excessive pesticide and herbicide use. By harnessing advanced technology, Agibot offers a transformative approach to agriculture through precise identification and targeted management of weeds, diseases, and pests. This capability not only enhances crop health and productivity but also mitigates the environmental consequences such as soil degradation, water contamination, and disruption of natural ecosystems. In contrast to traditional methods reliant on broad-spectrum chemicals, Agibot's real-time detection and intervention capabilities enable farmers to adopt sustainable practices that reduce chemical inputs while optimizing yield. This technological advancement represents a pivotal shift towards a more sustainable and resilient agricultural future, where Agibot plays a crucial role in balancing agricultural productivity with environmental stewardship, benefiting both farmers and global sustainability efforts.

Results

Agibot represents a significant advancement in agricultural technology, leveraging the YOLOv8 algorithm and a diverse dataset to swiftly and accurately detect weeds. This innovation reduces reliance on herbicides, promotes sustainable farming practices, and enhances crop protection and yield. Agibot's modular design supports the integration of additional sensors for comprehensive farm management, while its robust construction ensures durability in field operations. Overall, Agibot optimizes efficiency, minimizes environmental impact, and empowers farmers with actionable insights for proactive decision-making in modern agriculture.



Supervised By:

Prof. Dr. Magdy Abdel Azim
Dr. Wessam Mohammed Salama

Methodology

The methodology behind creating Agibot focused on leveraging advanced technology to address agricultural challenges effectively. This involved selecting the YOLOv8 algorithm for its rapid and precise real-time detection of harmful plants, optimizing for accuracy and speed. A diverse dataset was curated to train Agibot, ensuring robust performance across various agricultural environments. The robot's modular design facilitated integration with sensors specifically tailored for identifying and managing harmful plants, enhancing its functionality in targeted crop management. Field testing validated Agibot's performance under real-world conditions, allowing for iterative refinement to meet the practical needs of farmers. This approach not only improves agricultural efficiency but also promotes sustainable practices by reducing reliance on harmful chemicals, marking a significant advancement in precision farming technology.

Conclusion

Agibot revolutionizes precision farming by leveraging advanced technology to tackle agricultural challenges. Utilizing the YOLOv8 algorithm and an extensive weed database, Agibot excels in identifying and classifying weeds, diseases, and pests quickly and efficiently.

Its modular design and real-time data analysis enhance farm management and crop protection. The user-friendly interface and durable build ensure ease of use and long-lasting performance, reducing labor and time demands, making it indispensable in modern agriculture.

Focused on sustainable practices, Agibot's targeted threat detection minimizes herbicide use, underscoring its commitment to eco-friendly farming. By improving efficiency and promoting environmental stewardship, Agibot sets a new standard for precision farming and exemplifies the potential of innovation in achieving sustainable agriculture.

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